# SSL LC-800.x Photocurrent meter



**Back to Contents** 

### Advantages of new version for multichannel photocurrent meter

- Wider dynamic range of 9 decades
- 4-channels for separation of X channel to  $X_{red}$  and  $X_{blue}$
- Larger bandwidth at smaller photocurrents
- Improved sampling rate
- On-the-fly measurement compatible
- ☐ 1-4 Channel Transimpedance amplifier (TIA)
- Measurement quantities:
  - ✓ Illuminance Ev (Ix)
  - ✓ Effective Luminous Intensity
  - ✓ Flicker Index FI, Percent Flicker MI (%), Flicker Frequency (Hz)
  - √ Stroboscopic Visual Measure SVM
  - ✓ Short-term Perceptibility Light Modulation  $P_{st}^{LM}$
  - ✓ CCT (K), CIE1931 xy, CIE1976 u'v'
- ☐ 12V power supply
- □ Data communication: RS-232 (DB9), USB B 2.0
- ☐ Compatible with CH and LH measuring heads



Fig. Rear panel.

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**Back to Contents** 

Signal bandwidth*	Photocurrent range
15 kHz	200 nA – 18 mA
6 kHz	15 nA – 200 nA
700 Hz	1nA – 15 nA
50 Hz	30 pA – 1 nA
SVM requirement: > 2 kHz	15 nA – 18 mA

<sup>\*</sup> Optional: Bandwidth filter of 4kHz can be setup separately.

- ☐ Photocurrent measurement range:
  - $\checkmark$  30 pA 18 mA (high sensitivity acquisition mode)
  - ✓ 30 nA 18 mA (on-the-fly acquisition mode)
- ☐ Linearity < 0.1%
- ☐ Sampling rate
  - ✓ Timed sampling: 100 kHz (10µs)
  - ✓ Maximum: ~200 kHz (5µs)
  - √ SVM: 36 kHz (1s measuring time)
  - $\checkmark P_{st}^{LM}: 2 \text{ kHz (1-5min)}$
- ☐ Package includes: LC-800, 12V power supply, 1.8m USB cable, 1.8m RS-232 cable.

## SSL CH400x Color Measuring Head

**Back to Contents** 

New 4-channel tristimulus colorimeter head with common input optics

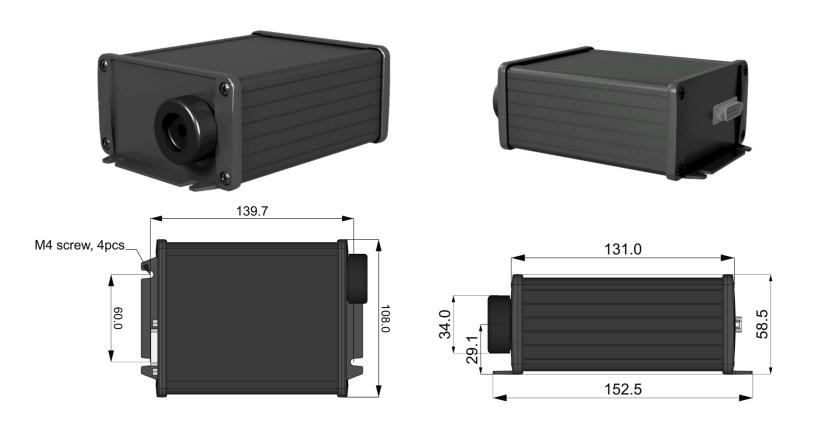
#### **Benefits:**

- √ No errors due to the drastic changes in light beam
- ✓ Shorter min. distance

#### Perfect solution for

- ✓ Sector light
- √ Goniocolorimeter

СН	Aperture (mm)	S <sub>Ev</sub> (nA/ Ix)	f <sub>1</sub> '	FOV (1)	Min. D <sup>(2)</sup> (m)	Illuminance range (lx)
CH4001	6.0	1.7	Y: 3% X <sub>r</sub> : 3%	10.4°	3.4	2 E-2 - 5 E+6
CH4002	14.4	10	X <sub>b</sub> : 3% Z: 3.5%	3.1°	8.3	3 E-3 - 8 E+5



<sup>(1)</sup> FOV = Detection field-of-view of each sensors.

<sup>(2)</sup> Min. D = Minimum distance to cover all sensors into the angular full field-of-view of 0.1° (corresponding angular accuracy in goniometric measurements).